Linear Algebra [KOMS119602] - 2022/2023

# 11.1 - Change of Basis

Dewi Sintiari

Computer Science Study Program Universitas Pendidikan Ganesha

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# Coordinates of general vector space

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## Coordinates of general vector space

#### Definition If $S = {\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n}$ is a basis for a vector space V, and

 $\mathbf{v}=c_1\mathbf{v}_1+c_2\mathbf{v}_2+\cdots+c_n\mathbf{v}_n$ 

Then the scalars  $c_1, c_2, \ldots, c_n$  are called coordinates vector of v relative to the basis S.

The vector  $\{c_1, c_2, \ldots, c_n\}$  in  $\mathbb{R}^n$  is called the coordinates vector of v relative to the basis S, and is denoted by

 $(\mathbf{v})_S = (c_1, c_2, \ldots, c_n)$ 

#### Remark.

A basis S of a vector space V is a set. This means that the order in which those vectors in S are listed does not generally matter.

To deal with this, we define ordered basis, which is the basis in which the listing order of the basis vectors remains fixed.

#### Coordinates of general vector space

 $\mathbf{v}_{S}$  is a vector in  $\mathbb{R}^{n}$ .

Once an ordered basis S is given for a vector space V, the "Uniqueness Theorem" establishes a one-to-one correspondence between vectors in V and vectors in  $\mathbb{R}^n$ .



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# Example 1: coordinates relative to the standard basis for $\mathbb{R}^n$

For the vector space  $V = \mathbb{R}^n$  and S is the standard basis, the coordinate vector  $(\mathbf{v})_S$  and the vector  $\mathbf{v}$  are the same;

$$\mathbf{v} = (\mathbf{v})_S$$

#### Example

For  $V = \mathbb{R}^3$ ,  $S = {\mathbf{i}, \mathbf{j}, \mathbf{k}}$ .

The representation of vector  $\mathbf{v} = (a, b, c)$  in the standard basis is:

$$\mathbf{v} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$$

The coordinate vector relative to the basis S is  $(\mathbf{v})_S = (a, b, c)$  (same as  $\mathbf{v}$ ).

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Example 2: coordinate vectors relative to standard bases

Find the coordinate vector for the polynomial:

$$\mathbf{p}(x) = c_0 + c_1 x + c_2 x^2 + \dots + c_n x^n$$

relative to the standard basis for the vector space  $P_n$ . Solution:

The standard basis for  $P_n$  is: = {1,  $x, x^2, ..., x^n$ }. So, the coordinate vector for **p** relative to *S* is:

$$(\mathbf{p})_{\mathcal{S}} = (c_0, c_1, c_2, \ldots, c_n)$$

#### Example 3: coordinate vectors relative to standard bases

Find the coordinate vector of:

$$B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

relative to the standard basis for  $M_{22}$ .

#### Solution:

The standard basis vectors for  $M_{22}$  is:

$$\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

Hence,

$$B = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

So, the coordinate vector of B relative to S is:

$$(B)_S=(a,b,c,d)$$

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#### Exercise 1

Show that the following set of vectors  $S = {\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3}$  form a basis of  $\mathbb{R}^3$ .

$$\textbf{v}_1=(1,2,1), \ \textbf{v}_2=(2,9,0), \ \textbf{v}_3=(3,3,4)$$

Find the coordinate vector of  $\mathbf{v} = (5, 1 - 9)$  relative to the basis S.

Solution: Question 1 (skipped)

Question 2:

We have to find the values  $c_1, c_2, c_3$  s.t.:

$$\mathbf{v} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3$$

or, in this case:

$$(5, 1-9) = c_1(1, 2, 1) + c_2(2, 9, 0) + c_3(3, 3, 4)$$

from which we can extract the linear equations system:

$$\begin{cases} c_1+2c_2+3c_3=5\\ 2c_1+9c_2+3c_3=-1\\ c_1+4c_3=9 \end{cases}$$

Solving the system, we obtain (verify it!):

$$c_1=1,\ c_2=-1,\ c_3=2$$

This means that:  $(\mathbf{v})_S = (1, -1, 2).$ 

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#### Exercise 2

Find the vector  ${\bf v}$  in  $\mathbb{R}^3$  whose coordinate vector relative to  $S=\{{\bf v}_1,{\bf v}_2,{\bf v}_3\}$  with

$$\textbf{v}_1=(1,2,1), \ \textbf{v}_2=(2,9,0), \ \textbf{v}_3=(3,3,4)$$

is  $(v)_S = (-1, 3, 2)$ .

#### Solution:

Let:  $(c_1, c_2, c_3) = (-1, 3, 2)$ . Hence,  $\mathbf{v} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3$  = (-1)(1, 2, 1) + 3(2, 9, 0) + 2(3, 3, 4)= (11, 31, 7)

So, the vector **v** for which  $(v)_{S} = (-1, 3, 2)$  is (11, 31, 7).

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# Change of basis

# Why change of basis needed?

• A basis that is suitable for one problem may not be suitable for another;

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#### Coordinate maps

Let  $S = {\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n}$  be a basis for a finite-dimensional vector space V. Let the coordinate vector of  $\mathbf{v}$  relative to S be:

$$(\mathbf{v})_S = (c_1, c_2, \ldots, c_n)$$

The one-to-one correspondence (mapping) between vectors in V and vectors in the Euclidean vector space  $\mathbb{R}^n$  is defined as;

$$\mathbf{v} o (\mathbf{v})_S$$

This is called the coordinate map relative to S from V to  $\mathbb{R}^n$ .

We will use column matrix to represent the coordinate vectors:

$$[\mathbf{v}]_{\mathcal{S}} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$

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# The Change-of-Basis Problem

**Problem:** If **v** is a vector in a finite-dimensional vector space V, and we change the basis for V from a basis B to another basis B', how are the coordinate vector  $[\mathbf{v}]_B$  and  $[\mathbf{v}]_{B'}$  related?

- In the literature, *B* is usually called the old basis and *B'* is called the new basis.
- For convenience, I will use the terms first basis and second basis.

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#### Solution of the Change-of-Basis problem (in 2-dimensional space) Let

$$B = \{\mathbf{u}_1, \mathbf{u}_2\}$$
 and  $B' = \{\mathbf{u}_1', \mathbf{u}_2'\}$ 

and the coordinate vectors for the 2nd basis relative to the 1st basis is:

$$[\mathbf{u}_1']_B = \begin{bmatrix} a \\ b \end{bmatrix}$$
 and  $[\mathbf{u}_2']_B = \begin{bmatrix} c \\ d \end{bmatrix}$ 

i.e., the following relation holds:

$$u'_1 = au_1 + bu_2$$
 (1)  
 $u'_2 = cu_1 + du_2$  (2)

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**Problem:** Given a vector  $\mathbf{v} \in V$ , with

$$[\mathbf{v}]_{B'} = \begin{bmatrix} k_1 \\ k_2 \end{bmatrix}$$

How to find the coordinate vector of  $\mathbf{v}$  relative to B?

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# Solution (cont.)

Since the coordinate vector of  $\mathbf{v}$  relative to B' is

$$[\mathbf{v}]_{B'} = \begin{bmatrix} k_1 \\ k_2 \end{bmatrix}$$

this means that:

$$\mathbf{v} = k_1 \mathbf{u}_1' + k_2 \mathbf{u}_2'$$

By the relation (1) and (2) in the previous slide, we have:

$$\mathbf{v} = k_1(a\mathbf{u}_1 + b\mathbf{u}_2) + k_2(c\mathbf{u}_1 + d\mathbf{u}_2)$$
  
=  $(k_1a + k_2c)\mathbf{u}_1 + (k_1b + k_2b)\mathbf{u}_2$ 

So, the coordinate vector of v relative to B is:

$$[\mathbf{v}]_B = \begin{bmatrix} k_1 + k_2 c \\ k_1 b + k_2 d \end{bmatrix}$$

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#### Finding transition matrices

The vector 
$$[\mathbf{v}]_B = \begin{bmatrix} k_1 + k_2 c \\ k_1 b + k_2 d \end{bmatrix}$$
 can be written as:  
 $[\mathbf{v}]_B = \begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} = \begin{bmatrix} a & c \\ b & d \end{bmatrix} [\mathbf{v}]_B$ 

Let 
$$P = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$$
. This means that:

the coordinate vector  $[\mathbf{v}]_B$  can be obtained by multiplying the coordinate vector  $[\mathbf{v}]_{B'}$  on the left by matrix *P*.

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## Solution of the Change-of-Basis Problem

#### Theorem

Let V be an n-dimensional space. If we want to change the basis for V from basis  $B = {\mathbf{u}_1, \mathbf{u}_2, ..., \mathbf{u}_n}$  to another basis  $B' = {\mathbf{u}'_1, \mathbf{u}'_2, ..., \mathbf{u}'_n}$ .

Then for each vector  $\mathbf{v} \in V$ , we have the following relation between  $[\mathbf{v}]_B$  and  $[\mathbf{v}]_{B'}$ , as follows:

$$[\mathbf{v}]_B = P[\mathbf{v}]_{B'}$$

where P is the matrix whose columns are the coordinate vectors of B' relative to B, i.e., the columns of P are:

 $[\mathbf{u}_1']_B, [\mathbf{u}_2']_B, \dots, [\mathbf{u}_n']_B$ 

*P* is called the transition matrix from *B'* to *B*, and is denoted by  $P_{B' \rightarrow B}$ .

$$P_{B' \to B} = \left[ \left[ \mathbf{u}_1' \right]_B \mid \left[ \mathbf{u}_2' \right]_B \mid \ldots \mid \left[ \mathbf{u}_n' \right]_B \right]$$
(1)

$$P_{B\to B'} = [ [\mathbf{u}_1]_{B'} | [\mathbf{u}_2]_{B'} | \dots | [\mathbf{u}_n]_{B'} ]$$
(2)

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#### Example 1: finding transition matrices

Given the bases  $B = {\mathbf{u}_1, \mathbf{u}_2}$  and  $B' = {\mathbf{u}'_1, \mathbf{u}'_2}$  for  $\mathbb{R}^2$ , where:

$$\mathbf{u}_1=(1,0), \ \mathbf{u}_2=(0,1), \ \mathbf{u}_1'=(1,1), \ \mathbf{u}_2'=(2,1)$$

- 1. Find the transition matrix  $P_{B' \rightarrow B}$  from B' to B.
- 2. Find the transition matrix  $P_{B \rightarrow B'}$  from B to B'.

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#### Solution of Example 1

**Solution 1:** The transition matrix  $P_{B' \rightarrow B}$  from B' to B.

$$\begin{aligned} \mathbf{u}_1' &= \mathbf{u}_1 + \mathbf{u}_2 \\ \mathbf{u}_2' &= 2\mathbf{u}_1 + \mathbf{u}_2 \end{aligned}$$

Hence,

So,

$$[\mathbf{u}_1']_B = \begin{bmatrix} 1\\1 \end{bmatrix}$$
 and  $[\mathbf{u}_2']_B = \begin{bmatrix} 2\\1 \end{bmatrix}$ 

$$P_{B'\to B} = \begin{bmatrix} 1 & 2\\ 1 & 1 \end{bmatrix}$$

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#### Solution of Example 1 (cont.)

**Solution 2:** The transition matrix  $P_{B \rightarrow B'}$  from B to B'.

$$\begin{split} \mathbf{u}_1 &= -\mathbf{u}_1' + \mathbf{u}_2' \\ \mathbf{u}_2 &= 2\mathbf{u}_1 - \mathbf{u}_2 \end{split}$$

Hence,

$$[\mathbf{u}_1]_{B'} = \begin{bmatrix} -1\\ 1 \end{bmatrix}$$
 and  $[\mathbf{u}_2]_{B'} = \begin{bmatrix} 2\\ -1 \end{bmatrix}$ 

So,

$$P_{B\to B'} = \begin{bmatrix} -1 & 2\\ 1 & -1 \end{bmatrix}$$

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### Example 2: computing coordinate vectors

#### Problem:

Given the bases  $B = \{\mathbf{u}_1, \mathbf{u}_2\}$  and  $B' = \{\mathbf{u}'_1, \mathbf{u}'_2\}$  for  $\mathbb{R}^2$ , where:

$$\mathbf{u}_1 = (1,0), \ \mathbf{u}_2 = (0,1), \ \mathbf{u}'_1 = (1,1), \ \mathbf{u}'_2 = (2,1)$$
  
Find the vector  $[\mathbf{v}]_B$  given that  $[\mathbf{v}]_{B'} = \begin{bmatrix} -3\\5 \end{bmatrix}$ .

Solution:

$$[\mathbf{v}]_B = P_{B' \to B}[\mathbf{v}]_{B'} = \begin{bmatrix} 1 & 2\\ 1 & 1 \end{bmatrix} \begin{bmatrix} -3\\ 5 \end{bmatrix} = \begin{bmatrix} 7\\ 2 \end{bmatrix}$$

#### Invertibility of transition matrices

What happen if we multiply  $P_{B' \rightarrow B}$  with  $P_{B \rightarrow B'}$ ?

- We first map the *B*-coordinates of **v** into its *B*'-coordinates;
- then map the B'-coordinates of **v** into its B-coordinates;
- This yields that **v** is back to its *B*-coordinates.

$$P_{B'\to B}P_{B\to B'}=P_{B\to B}=I$$

#### Example

Read again Example 1.

$$(P_{B'\to B})(P_{B\to B'}) = \begin{bmatrix} 1 & 2\\ 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 2\\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0\\ 0 & 1 \end{bmatrix} = I$$

#### Theorem

 $P_{B' \to B}$  is invertible, and its inverse is  $P_{B \to B'}$ .

# A procedure for computing $P_{B \rightarrow B'}$

#### Procedure:

- 1. Form the matrix [B' | B|];
- 2. Use elementary row operations to reduce the matrix in Step 1 to reduced row echelon form;
- 3. The resulting matrix will be  $[I | P_{B \rightarrow B'}]$ ; Extract the matrix  $P_{B \rightarrow B'}$  from the right side of the matrix in Step 3.

#### Diagram:

$$\begin{bmatrix} B' \mid B \end{bmatrix} \xrightarrow{\text{row operations}} \begin{bmatrix} I \mid \text{transition from } B \text{ to } B' \end{bmatrix}$$
(1)

#### Exercise

In Example 1, we are given the bases  $B = \{\mathbf{u}_1, \mathbf{u}_2\}$  and  $B' = \{\mathbf{u}'_1, \mathbf{u}'_2\}$  for  $\mathbb{R}^2$ , where:

$$\mathbf{u}_1=(1,0), \ \mathbf{u}_2=(0,1), \ \mathbf{u}_1'=(1,1), \ \mathbf{u}_2'=(2,1)$$

Use formula (1) of the previous slide to find:

- 1. The transition matrix from B' to B.
- 2. The transition matrix from B to B'.

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# Solution of exercise

Question 1.

$$\left[B'\mid B
ight] = egin{bmatrix} 1 & 0 \mid 1 & 2 \ 0 & 1 \mid 1 & 1 \end{bmatrix}$$

Since the left side is already the identity matrix, no reduction is needed. Hence,

$$P_{B'\to B} = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$$

Question 2.

$$\left[B'\mid B
ight]=egin{bmatrix}1&2\mid 1&0\1&1\mid 0&1\end{bmatrix}$$

By reducing the matrix, we obtain:

$$P_{B \to B'} = \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix}$$

$$P_{B \to B'} = \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix}$$

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# Exercise (at home)

Given a basis  $B = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  and  $B' = \{\mathbf{u}_1', \mathbf{u}_2', \mathbf{u}_3'\}$  for  $\mathbb{R}^2$ , where:

- 1. Find the transition matrix from B to B'.
- 2. Find the transition matrix from the standard basis of  $\mathbb{R}^3$  to B.
- 3. Find the transition matrix from the standard basis of  $\mathbb{R}^3$  to B'.
- 4. Find the coordinate vector **w** relative to basis *B*, if the coordinate vector **w** relative to the standard basis *S* is  $[\mathbf{w}]_S = (-5, 8, -5)$ .

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to be continued...

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